



Memory Management

Chapter 7

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Memory Management

- Subdividing memory to accommodate multiple processes
- Memory needs to be allocated efficiently to pack as many processes into memory as possible

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Memory Management Requirements

- Relocation
 - Programmer does not know where the program will be placed in memory when it is executed
 - While the program is executing, it may be swapped to disk and returned to main memory at a different location (relocated)
 - Memory references must be translated in the code to actual physical memory address

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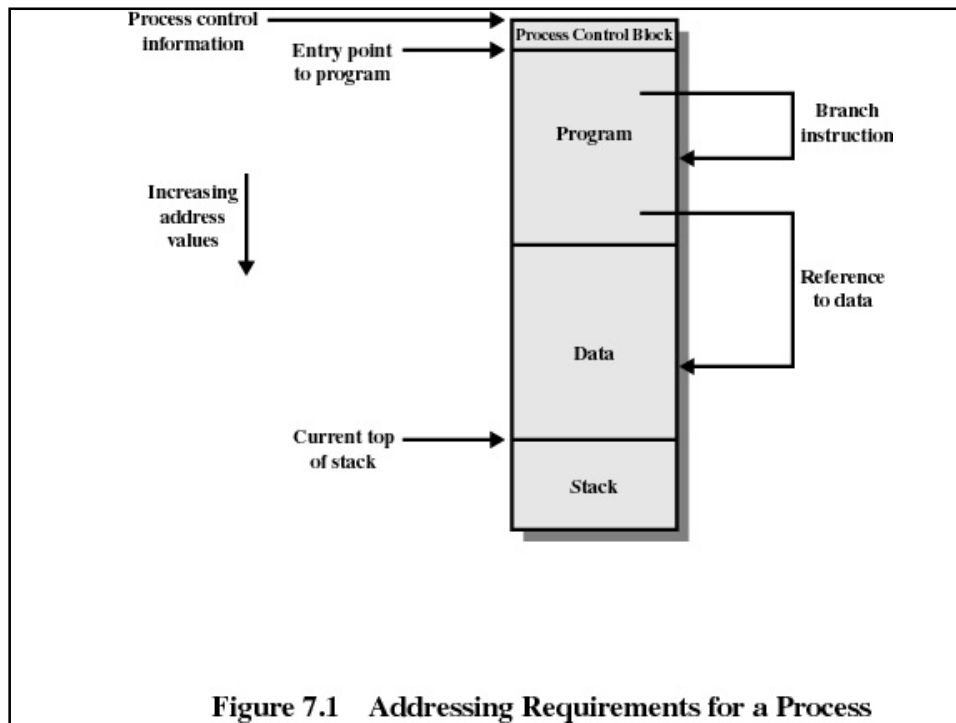


Figure 7.1 Addressing Requirements for a Process



Memory Management Requirements

- Protection
 - Processes should not be able to reference memory locations in another process without permission
 - Impossible to check absolute addresses in programs since the program could be relocated
 - Must be checked during execution
 - Operating system cannot anticipate all of the memory references a program will make

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Memory Management Requirements

- Sharing
 - Allow several processes to access the same portion of memory
 - Better to allow each process (person) access to the same copy of the program rather than have their own separate copy

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Memory Management Requirements

- Logical Organization
 - Programs are written in modules
 - Modules can be written and compiled independently
 - Different degrees of protection given to modules (read-only, execute-only)
 - Share modules

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Memory Management Requirements

- Physical Organization
 - Memory available for a program plus its data may be insufficient
 - Overlaying allows various modules to be assigned the same region of memory
 - Programmer does not know how much space will be available

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Fixed Partitioning

- Equal-size partitions
 - any process whose size is less than or equal to the partition size can be loaded into an available partition
 - if all partitions are full, the operating system can swap a process out of a partition
 - a program may not fit in a partition. The programmer must design the program with overlays

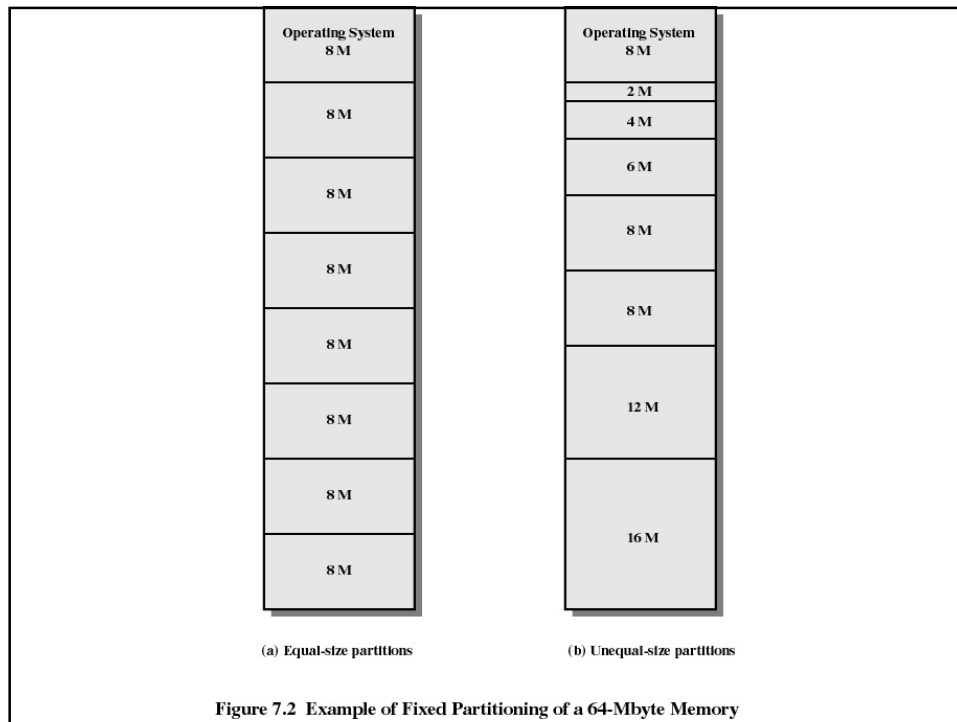
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Fixed Partitioning

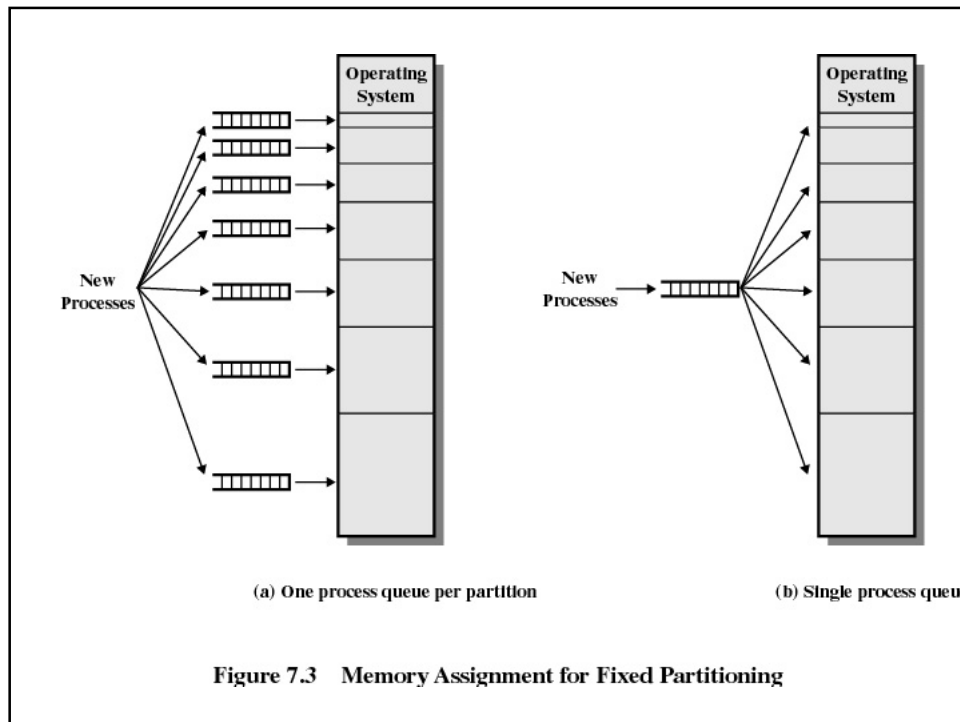
- Main memory use is inefficient. Any program, no matter how small, occupies an entire partition. This is called internal fragmentation.

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Placement Algorithm with Partitions

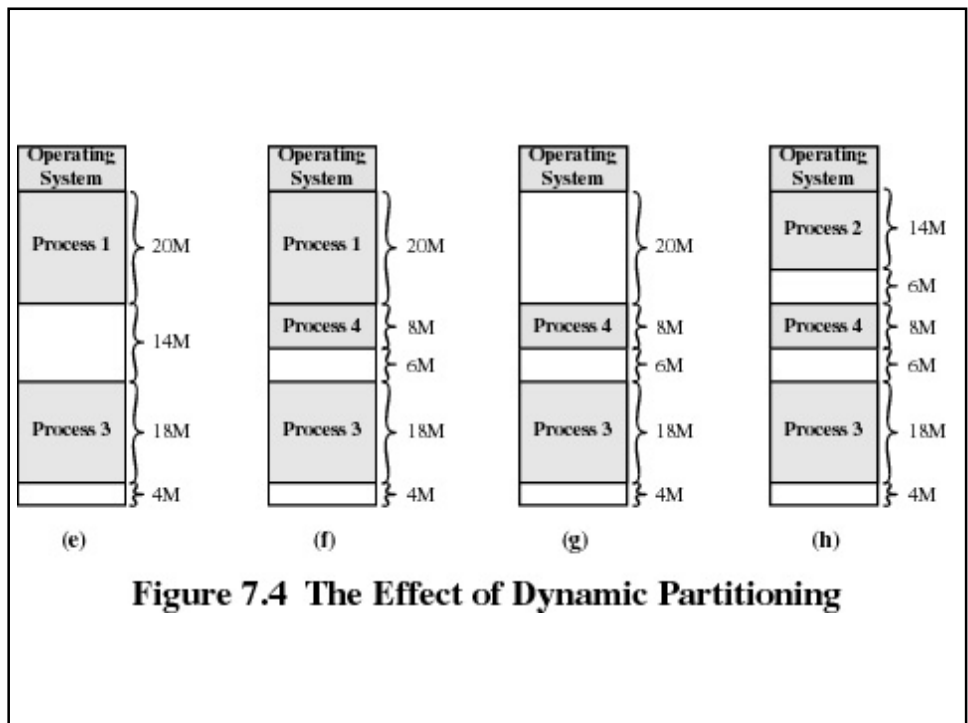
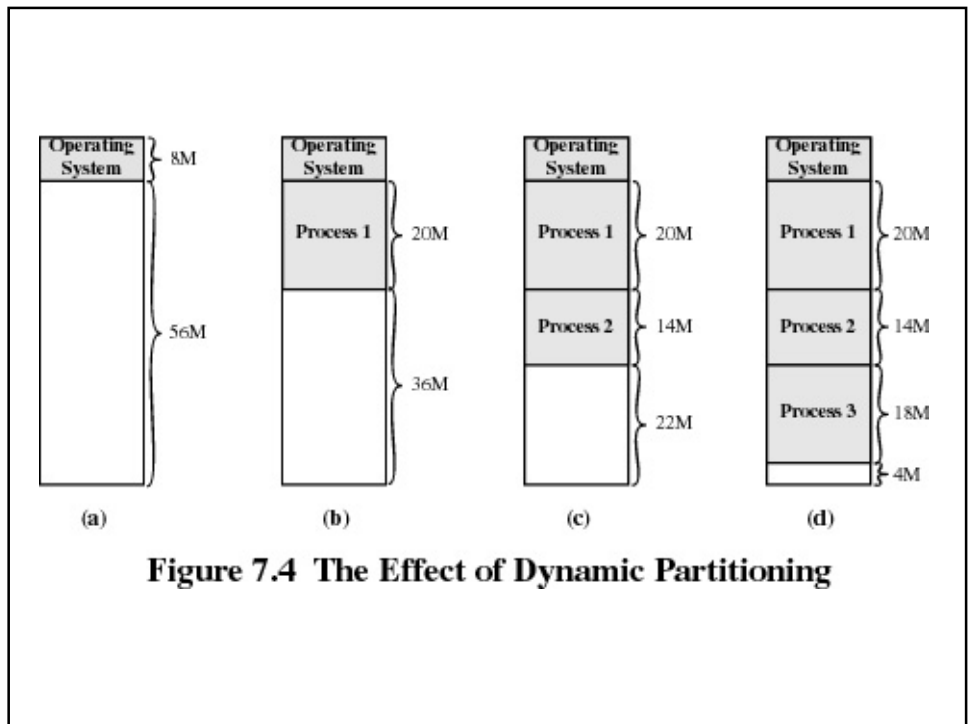
- Equal-size partitions
 - because all partitions are of equal size, it does not matter which partition is used
- Unequal-size partitions
 - can assign each process to the smallest partition within which it will fit
 - queue for each partition
 - processes are assigned in such a way as to minimize wasted memory within a partition



Dynamic Partitioning

- Partitions are of variable length and number
- Process is allocated exactly as much memory as required
- Eventually get holes in the memory. This is called external fragmentation
- Must use compaction to shift processes so they are contiguous and all free memory is in one block

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Dynamic Partitioning Placement Algorithm

- Operating system must decide which free block to allocate to a process
- Best-fit algorithm
 - Chooses the block that is closest in size to the request
 - Worst performer overall
 - Since smallest block is found for process, the smallest amount of fragmentation is left memory compaction must be done more often

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Dynamic Partitioning Placement Algorithm

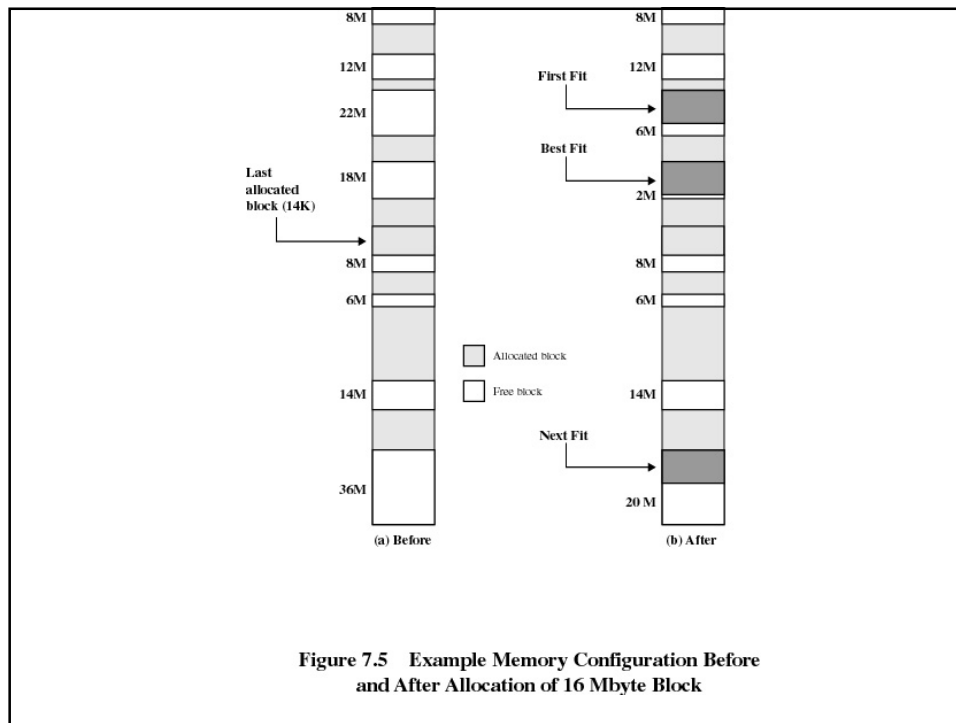
- First-fit algorithm
 - Fastest
 - May have many processes loaded in the front end of memory that must be searched over when trying to find a free block

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Dynamic Partitioning Placement Algorithm

- Next-fit
 - More often allocate a block of memory at the end of memory where the largest block is found
 - The largest block of memory is broken up into smaller blocks
 - Compaction is required to obtain a large block at the end of memory

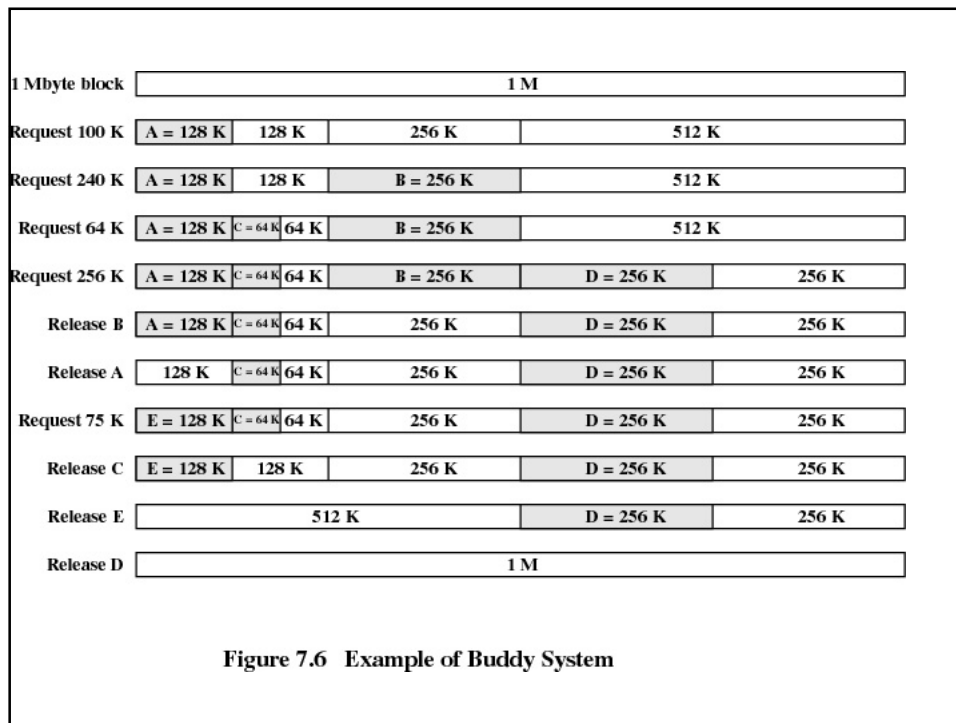
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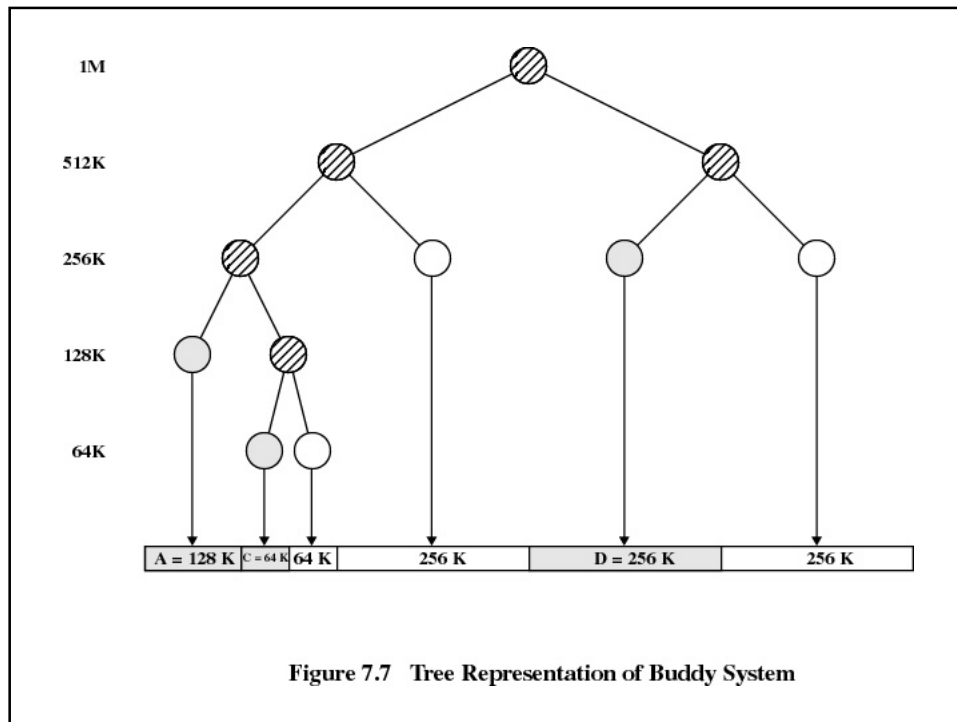


Buddy System

- Entire space available is treated as a single block of 2^U
- If a request of size s such that $2^{U-1} < s \leq 2^U$, entire block is allocated
 - Otherwise block is split into two equal buddies
 - Process continues until smallest block greater than or equal to s is generated

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Relocation

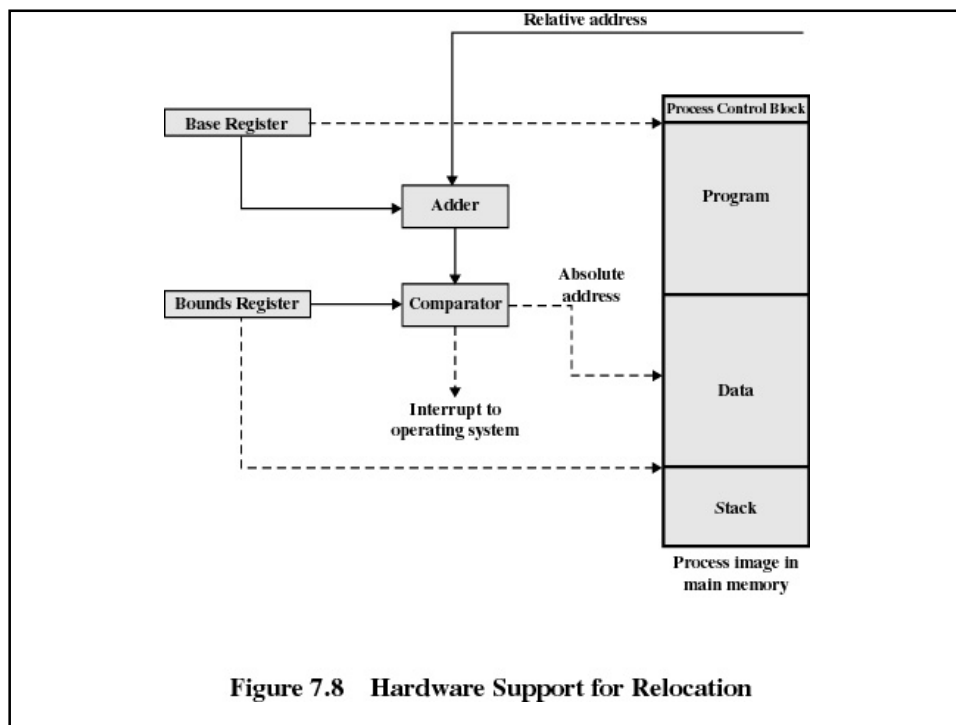
- When program loaded into memory the actual (absolute) memory locations are determined
- A process may occupy different partitions which means different absolute memory locations during execution (from swapping)
- Compaction will also cause a program to occupy a different partition which means different absolute memory locations

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Addresses

- Logical
 - reference to a memory location independent of the current assignment of data to memory
 - translation must be made to the physical address
- Relative
 - address expressed as a location relative to some known point
- Physical
 - the absolute address or actual location in main memory

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Registers Used during Execution

- Base register
 - starting address for the process
- Bounds register
 - ending location of the process
- These values are set when the process is loaded and when the process is swapped in

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Registers Used during Execution

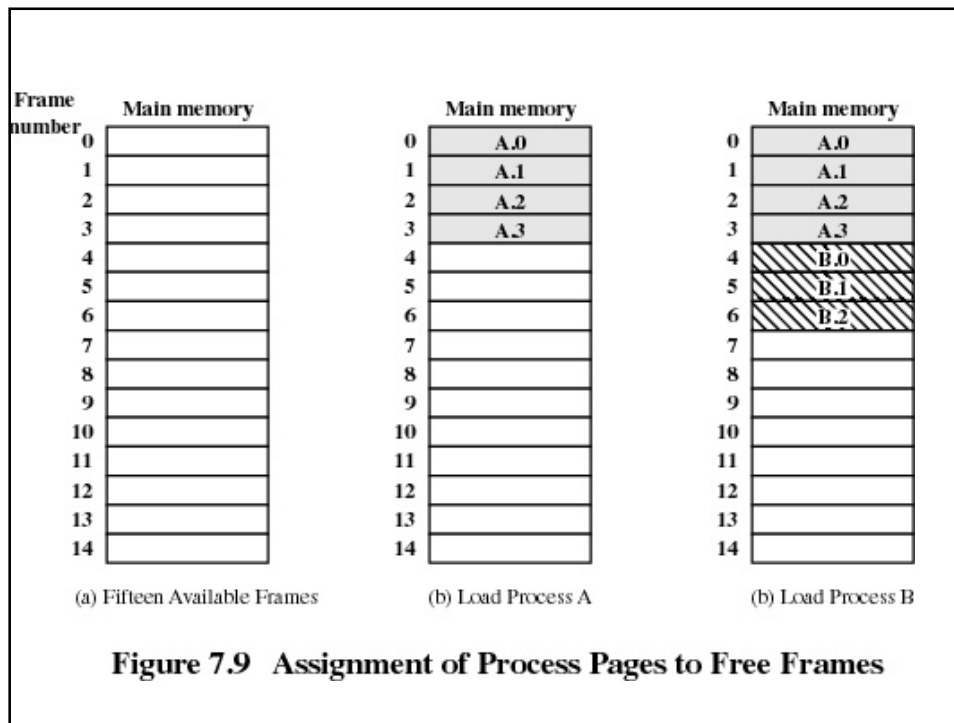
- The value of the base register is added to a relative address to produce an absolute address
- The resulting address is compared with the value in the bounds register
- If the address is not within bounds, an interrupt is generated to the operating system

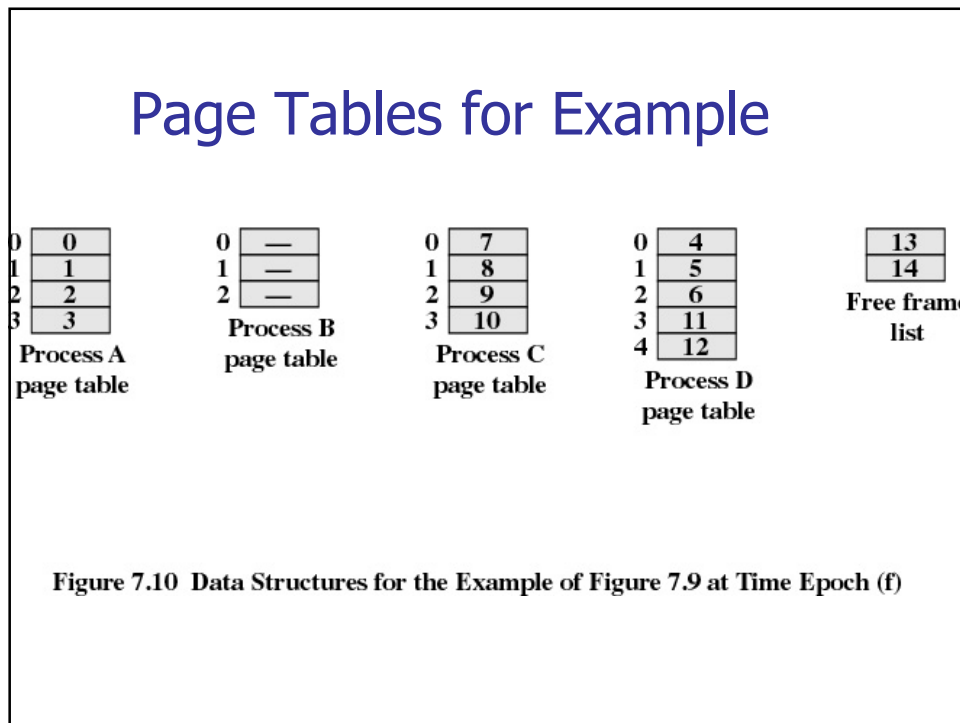
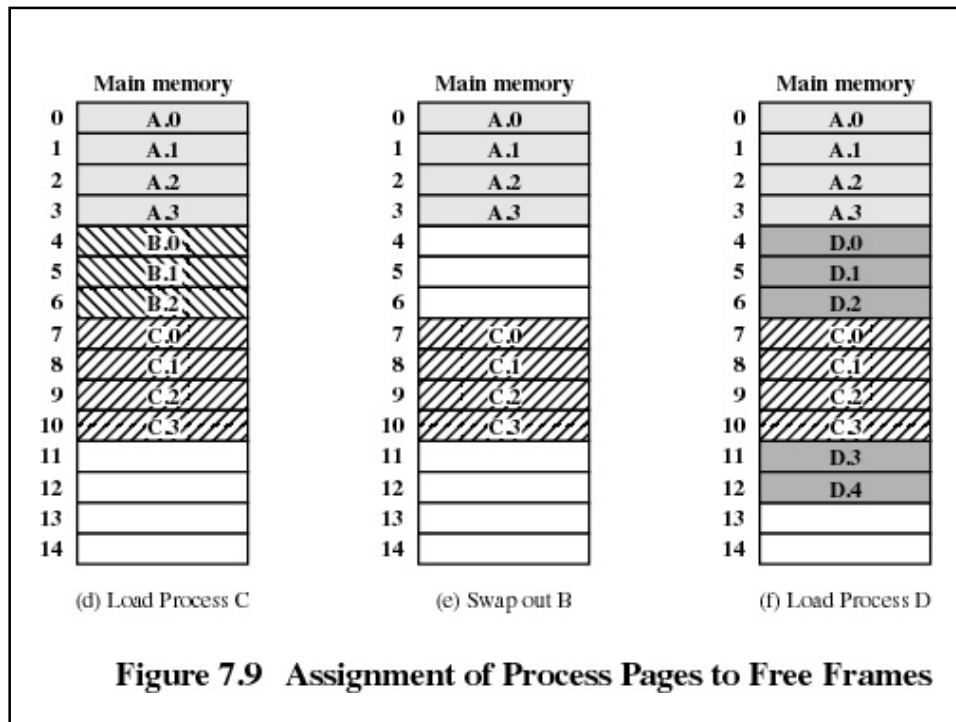
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Paging

- Partition memory into small equal-size chunks and divide each process into the same size chunks
- The chunks of a process are called pages and chunks of memory are called frames
- Operating system maintains a page table for each process
 - contains the frame location for each page in the process
 - memory address consist of a page number and offset within the page

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Segmentation

- All segments of all programs do not have to be of the same length
- There is a maximum segment length
- Addressing consist of two parts - a segment number and an offset
- Since segments are not equal, segmentation is similar to dynamic partitioning